

Super-resolution Radar

Reinhard Heckel

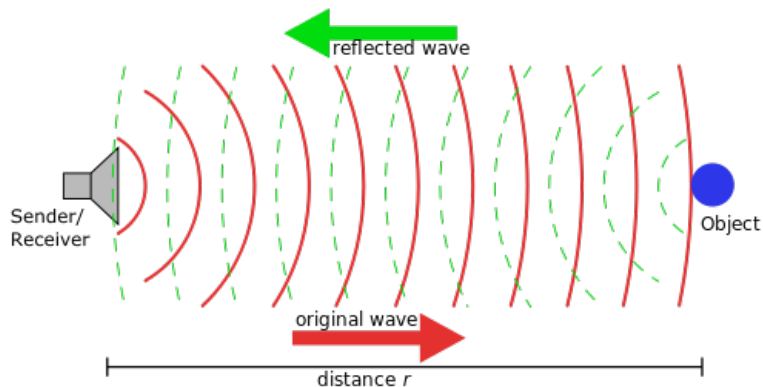
IBM Research (before: ETH Zurich)

June 25, 2015

Joint work with:

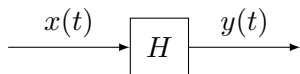
V. Morgenshtern and M. Soltanolkotabi

Motivation: Radar



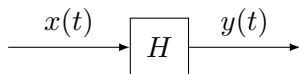
Goal: determine location and velocities of objects

Time-varying linear system H :



$$y(t) = \iint s_H(\tau, \nu) x(t - \tau) e^{i2\pi\nu t} d\nu d\tau$$

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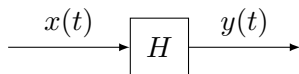


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Goal: Determine the triplets $(b_j, \bar{\tau}_j, \bar{\nu}_j)$ from I/O-measurement

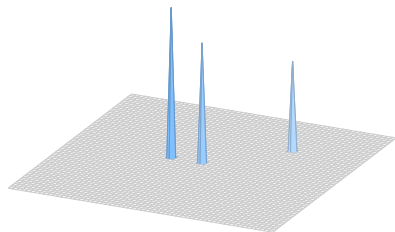
Band and time-limitation

In practice: $x(t)$ bandlimited to $[0, B]$ and $y(t)$ observed on $[0, T]$

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$$s_H(\tau, \nu)$$



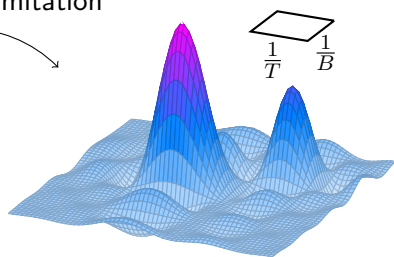
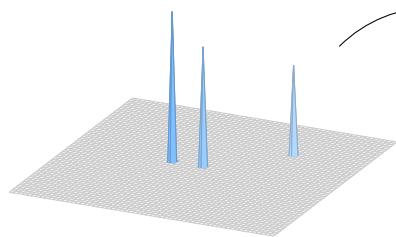
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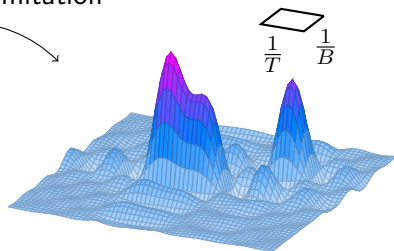
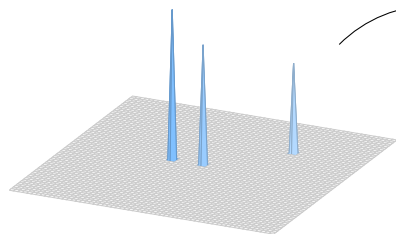
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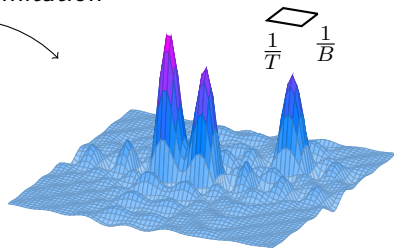
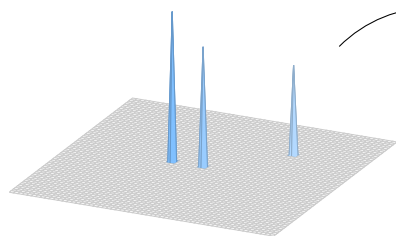
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band and time-limitation



Standard pulse-Doppler radar

Standard radar

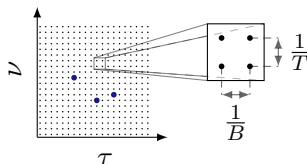
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Delay-Doppler pairs are resolved only on a grid:

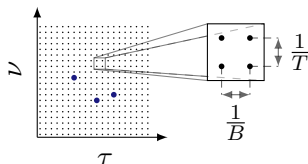


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Resolution achieved is $(\frac{1}{B}, \frac{1}{T})!$

The aim of this talk

Show that we can recover the delay-Doppler shifts **perfectly** via convex optimization even when

- x is bandlimited to $[0, B]$ and y is only observed on $[0, T]$
- the delays and Doppler shifts are large, i.e.,

$$(\bar{\tau}_j, \bar{\nu}_j) \in [0, T] \times [0, B]$$

Discretization through band and time limitation

Let $L = BT$

$$x(t) = \sum_{\ell=0}^{3L-1} x_{\ell} \operatorname{sinc}(tB - \ell), \quad x_{\ell} \text{ is } L \text{ periodic}$$

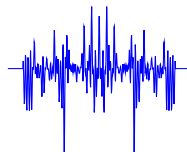
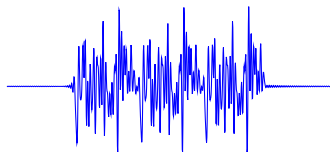
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$X(f)$



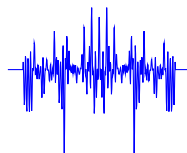
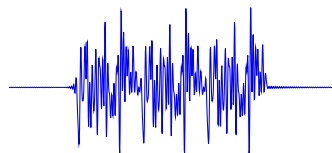
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Due to path loss and finite velocity of the targets we may assume:

$$(\bar{\tau}_j, \bar{\nu}_j) \in [0, T] \times [0, B]$$

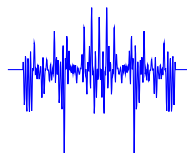
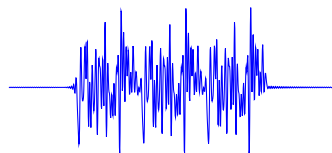
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$y(t)$ is band and essentially time limited as well, and on the order of BT -dimensional

Discretization through band and time limitation

Sampling at rate $1/B$ in the interval $[0, T]$ yields:

$$y_p = \sum_{j=1}^S b_j [\mathcal{F}_{\nu_j} \mathcal{T}_{\tau_j} \mathbf{x}]_p, \quad p = 0, \dots, L-1$$

where

$$\tau_j = \frac{\bar{\tau}_j}{T} \in [0, 1], \quad \nu_j = \frac{\bar{\nu}_j}{B} \in [0, 1], \quad \mathbf{x} = [x_0, \dots, x_{L-1}]$$

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$$[\mathcal{F}_{\nu} \mathbf{x}]_p = x_p e^{i2\pi p \nu}, \quad [\mathcal{T}_{\tau} \mathbf{x}]_p = [\mathbf{x}]_{p-L\tau}$$

The super-resolution Radar problem

Determine the **continuous** time-frequency shifts $(\tau_j, \nu_j) \in [0, 1]^2$ from the samples

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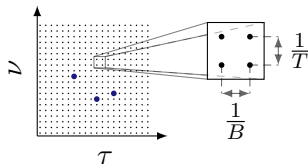
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This talk: Provably recovery of the time-frequency pairs via convex optimization

Compressed sensing Radar [*Herman & Storer, 2009*]

Suppose the $(\bar{\tau}_j, \bar{\nu}_j)$ lie on a $(\frac{1}{B}, \frac{1}{T})$ -grid



Then $\tau_j L$ and $\nu_j L$ are integers:

$$y_p = \sum_{j=1}^S b_j x_{p-(\tau_j L)} e^{i2\pi \frac{(\nu_j L)p}{L}} \quad p = 0, \dots, L - 1$$

Compressive sensing Radar

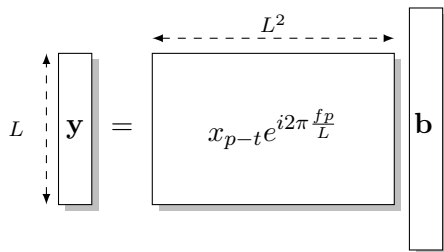
The diagram illustrates the equation $\mathbf{y} = \mathbf{A} \mathbf{b}$ for a compressive sensing radar system. The vector \mathbf{y} on the left has a height of L , indicated by a vertical dashed arrow. The matrix \mathbf{A} in the center is a square with a width of L^2 , indicated by a horizontal dashed arrow. The matrix contains the expression $x_{p-t} e^{i2\pi \frac{fp}{L}}$. The vector \mathbf{b} on the right is a tall, narrow vertical vector.

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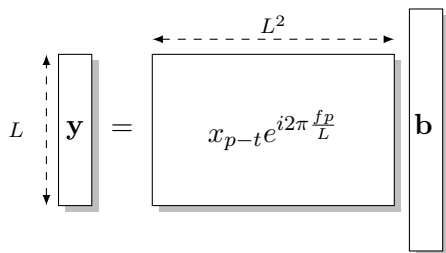
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- Resolution achieved by compressive sensing Radar is $(\frac{1}{B}, \frac{1}{T})!$

Special case: Frequency shifts only

If $\tau_j = 0$, the problem reduces to a line spectral estimation problem:

$$y_p = x_p \sum_{j=1}^S b_j e^{i2\pi p\nu_j}, \quad p = 0, \dots, L - 1$$

Special case: Time shifts only

If $\nu_j = 0$, the problem reduces to a line spectral estimation problem in the Fourier domain:

$$Y_p = X_p \sum_{j=1}^S b_j e^{i2\pi p\tau_j}, \quad p = 0, \dots, L - 1$$

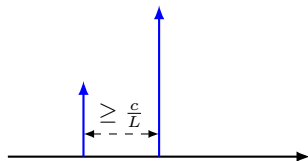
Recovery approaches for line spectral estimation

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Recovery approaches for line spectral estimation

- **Classical:** Prony's method, MUSIC, ESPRIT
- **Modern:** Recovery via convex optimization [*Candès & Fernandez-Granda, 2014*]: Recovery is possible provided the minimum separation condition holds:

$$|\nu_j - \nu_i| \geq \frac{4}{L}, \quad \text{for all } j \neq i$$



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Some sort of separation between the time-frequency shifts is necessary!

Recovery via convex programming

Recovery via “ ℓ_1 -minimization”:

$$\text{minimize } \sum_j |b_j| \text{ subject to } \mathbf{y} = \sum_j b_j \mathcal{F}_{\nu_j} \mathcal{T}_{\tau_j} \mathbf{x}$$

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- If the (τ_j, ν_j) lie on an **arbitrarily fine grid**, this is standard ℓ_1 -minimization
- Formal versions for continuous (τ_j, ν_j) :
 - Total-variation norm minimization [*Candès & Fernandez-Granda, 2014*]
 - Atomic norm minimization [*Bhaskar et al., 2013*], [*Tang et al., 2013*]

Recovery results for the super-resolution Radar problem

Main result

- Random probing signal: x_ℓ i.i.d. $\mathcal{N}(0, 1/L)$
- Random signs: sign of b_j is i.i.d. uniform on the real or complex unit sphere

Theorem

Let $\mathbf{y} = \sum_{j=1}^S b_j \mathcal{F}_{\nu_j} \mathcal{T}_{\tau_j} \mathbf{x}$. With probability $\geq 1 - \delta$, $(\tau_j, \nu_j, b_j), j = 1, \dots, S$, is the unique solution to ℓ_1 -minimization if

$$|\tau_j - \tau_i| \geq \frac{5}{L} \text{ or } |\nu_j - \nu_i| \geq \frac{5}{L}, \text{ for all } i \neq j$$

and if

$$S \leq cL \log^{-3} \left(\frac{L^6}{\delta} \right)$$

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- Essentially optimal

Implications for the continuous setup

The delay-Doppler shifts $\bar{\tau}_j, \bar{\nu}_j$ can be recovered perfectly provided that:

$$|\bar{\tau}_j - \bar{\tau}_i| \geq \frac{5}{B} \text{ or } |\bar{\nu}_j - \bar{\nu}_i| \geq \frac{5}{T}, \text{ for all } i \neq j$$

and

$$S \leq cBT \log^{-3} \left(\frac{(BT)^6}{\delta} \right)$$

Optimality condition

Lemma

Let $\mathbf{y} = \sum_{j=1}^S b_j \mathcal{F}_{\nu_j} \mathcal{T}_{\tau_j} \mathbf{x}$. If there exists a polynomial of the form

$$Q(\tau, \nu) = (\mathcal{F}_{\nu} \mathcal{T}_{\tau} \mathbf{x})^H \mathbf{q}$$

such that Q is **bounded** and **interpolates** the sign pattern of the signal:

$$Q(\tau_j, \nu_j) = \text{sign}(b_j), \quad \text{for all } j = 1, \dots, S$$

$$|Q(\tau, \nu)| < 1, \quad \text{for all other } (\tau, \nu)$$

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Q certifies the optimality of (b_j, τ_j, ν_j)

Proof of optimality condition

For simplicity, suppose the τ_j, ν_j lie on a grid

$$\text{Let } \mathbf{y} = \sum_{j=1}^S b_j \mathcal{F}_{\nu_j} \mathcal{T}_{\tau_j} \mathbf{x}$$

For all a_k, τ_k, ν_k with $\mathbf{y} = \sum_k a_k \mathcal{F}_{\nu_k} \mathcal{T}_{\tau_k} \mathbf{x}$:

$$\sum_k |a_k| \geq \sum_k |b_k| + \text{Re} \sum_k Q^*(\tau_k, \nu_k)(a_k - b_k)$$

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Proof is inspired by the construction of related certificates:

- Candès and Fernandez-Granda, “Towards a Mathematical Theory of Super-Resolution”
- Tang et al., “Compressed Sensing Off the Grid”

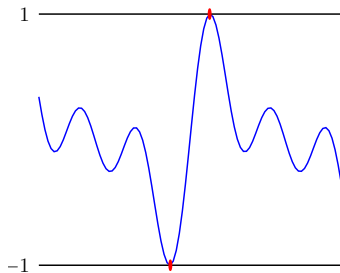
Certificate for $2D$ line spectral estimation

[*Candès and Fernandez-Granda, 2014*]:

For all b_j and (τ_j, ν_j) satisfying the **minimum separation condition** there exists a polynomial:

$$\bar{Q}(\tau, \nu) = \sum_{k,p=-L/2}^{L/2} \bar{q}_{k,p} e^{-i2\pi(k\tau+p\nu)}$$

that is **bounded** and **interpolates** $\text{sign}(b_j)$ at (τ_j, ν_j)



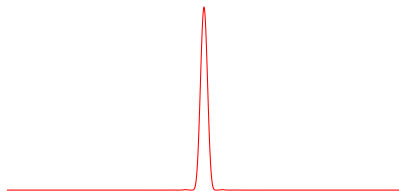
Construction of certificate for $2D$ line spectral estimation

[*Candès and Fernandez-Granda, 2014*]:

Construct \bar{Q} explicitly by interpolating $\text{sign}(b_j)$ with a kernel \bar{G} (and its partial derivatives $\bar{G}^{(1,0)}, \bar{G}^{(0,1)}$):

$$\bar{Q}(\tau, \nu) = \sum_{j=1}^S \alpha_j \bar{G}(\tau - \tau_j, \nu - \nu_j) + \dots$$

Interpolation with fast-decaying low-frequency kernel $\bar{G}(\tau, \nu)$:



Construction of certificate for time-frequency shifts

Interpolation with functions $G_{(\tau_j, \nu_j)}(\tau, \nu)$ that reach their maxima close to (τ_j, ν_j) and decay fast around its maxima

Interpolating functions

Q is a $2D$ trigonometric polynomial with certain coefficients:

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$$Q(\tau, \nu) = (\mathcal{F}_\nu \mathcal{T}_\tau \mathbf{x})^H \mathbf{q} = \sum_{k, \ell=-L/2}^{L/2} [\mathbf{F} \mathbf{G}^H \mathbf{q}]_{p, k} e^{-i2\pi(k\tau + p\nu)}$$

- $\mathbf{G} \in \mathbb{C}^{L \times L^2}$ is the Gabor matrix with columns $\mathcal{F}_{p/L} \mathcal{T}_{k/L} \mathbf{x}$
- \mathbf{F} : $2D$ DFT-matrix

Interpolating functions

Q is a $2D$ trigonometric polynomial with certain coefficients:

$$Q(\tau, \nu) = (\mathcal{F}_\nu \mathcal{T}_\tau \mathbf{x})^H \mathbf{q} = \sum_{k, \ell = -L/2}^{L/2} [\mathbf{F} \mathbf{G}^H \mathbf{q}]_{p, k} e^{-i2\pi(k\tau + p\nu)}$$

- $\mathbf{G} \in \mathbb{C}^{L \times L^2}$ is the Gabor matrix with columns $\mathcal{F}_{p/L} \mathcal{T}_{k/L} \mathbf{x}$
- \mathbf{F} : $2D$ DFT-matrix

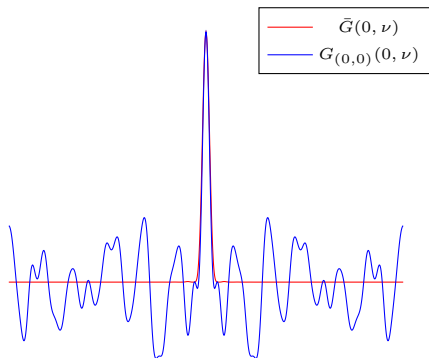
Interpolating functions:

$$G_{(\tau_j, \nu_j)}(\tau, \nu) = \underbrace{[\dots e^{i2\pi(\tau r + \nu q)} \dots]}_{(\mathcal{F}_\nu \mathcal{T}_\tau \mathbf{x})^H} \mathbf{F} \mathbf{G}^H \mathbf{G} \mathbf{F}^H \begin{bmatrix} \vdots \\ g_r g_q e^{-i2\pi(\tau_j r + \nu_j q)} \\ \vdots \end{bmatrix}$$

g_k are coefficients of fast decaying low-frequency kernel

Interpolating functions

$$\mathbb{E} \left[G_{(\tau_j, \nu_j)}(\tau, \nu) \right] = \bar{G}(\tau - \tau_j, \nu - \nu_j)$$



Final steps of the proof

Step 1: With high probability there exist interpolation coefficients such that G (and its derivatives) interpolate $\text{sign}(b_j)$

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- Step 1: With high probability there exist interpolation coefficients such that G (and its derivatives) interpolate $\text{sign}(b_j)$
- Step 2: With those interpolations coefficients, Q is bounded with high probability uniformly for all (τ, ν) not in the support set

Practical implementations

Recovery of the time-frequency shifts via the dual

The coefficient vector \mathbf{q} is a solution to the dual of ℓ_1 -minimization:

$$\text{maximize}_{\mathbf{q}} \text{Re} \langle \mathbf{q}, \mathbf{y} \rangle \quad \text{subject to} \quad \sup_{\tau, \nu} |(\mathcal{F}_\nu \mathcal{T}_\tau \mathbf{x})^H \mathbf{q}| \leq 1$$

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- Constraint says that a $2D$ -trigonometric polynomial is bounded in magnitude by 1
- Can be characterized by linear matrix inequalities [*Dumitrescu, 2006*]
- Dimensions of the matrices in this characterization are unspecified, fixing them leads to a relaxation

Recovery of the time-frequency shifts via the dual

Algorithm:

- 1 Solve the semidefinite programming relaxation to obtain \mathbf{q}
- 2 Identify the time frequency shifts as:
 $\{(\tau, \nu): |(\mathcal{F}_\nu \mathcal{T}_\tau \mathbf{x})^H \mathbf{q}| = 1\}$

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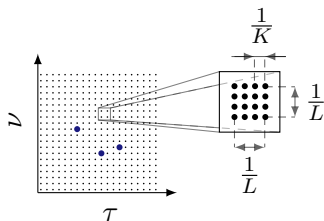
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However: Cost of solving the semidefinite programming relaxation is high!

Practical implementation by discretizing the domain

Suppose the (τ_j, ν_j) lie on a **fine grid**:

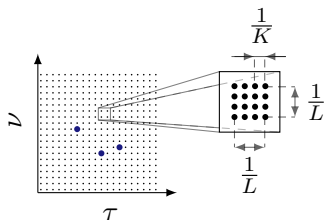


Super resolution factor: $\text{SRF} = K/L$

Recovery via ℓ_1 -minimization on the fine grid

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Structure can be used to accelerate this approach

Stability

Recovery via basis pursuit denoising:

$$\underset{\mathbf{b}}{\text{minimize}} \sum_j |b_j| \text{ subject to } \left\| \mathbf{y} - \sum_j b_j \mathcal{F}_{\nu_j} \mathcal{T}_{\tau_j} \mathbf{x} \right\|_2 \leq \delta$$

Minimization is over the b_j and (ν_j, τ_j) on the fine grid

Stability

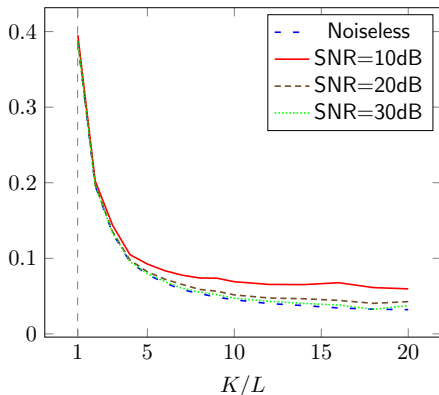
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Resolution error:

$$L \sqrt{(\hat{\tau}_j - \tau_j)^2 + (\hat{\nu}_j - \nu_j)^2}$$



Conclusion

Problem: Estimate the **continuous** time-frequency shifts (τ_j, ν_j) from

$$\mathbf{y} = \sum_{j=1}^S b_j \mathcal{F}_{\nu_j} \mathcal{T}_{\tau_j} \mathbf{x}$$

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- Minimum separation condition holds
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